

# Empirical Performance Assessment

## Black Box Optimization Benchmarking

# Black-Box Optimization Benchmarking

- assert / compare **quantitatively** performances
- gain some knowledge on algorithms
- select algorithms
- help to design new algorithms

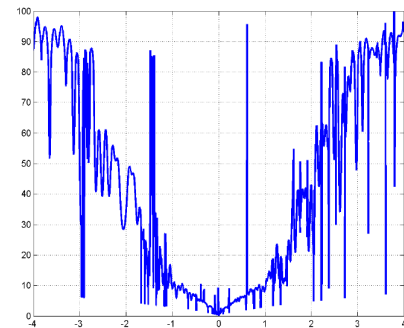
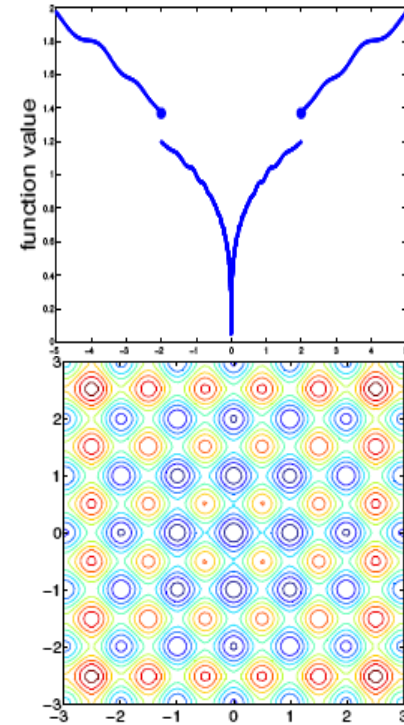
- Test functions
- Experimental setup
- How to measure performance

# Test functions

- Many real world problems share common difficulties:
  - non separability (correlations between variables)
  - ill-conditioned (certain direction steeper than others),
  - ruggedness (noise, ...),
  - multi-modality
  - non-convexity

*Ideally an optimizer should cope with all of them*

- Test functions chosen to assert on the performances w.r.t. those difficulties
  - non-noisy testbed (24 noise-free functions)
  - noisy testbed (30 noisy functions)
- Scalable with search space dimension
- Not too easy to solve but yet comprehensible



# Noiseless Functions

24 functions within **five sub-groups**

- **Separable** functions
- **Low or moderate conditioned** functions
- **Ill-conditioned** functions
- **Multimodal structured** functions
- **Multimodal** function with weak or without structure

Optimum of each function sampled uniformly in  $[-4, 4]^d$

For non separable functions, rotation sampled randomly for the different instances

# The Noisy Functions

three noise-”models”, so-called:

- Gauss, Uniform (severe), Cauchy (outliers)

30 functions with three sub-groups

- 2x3 functions with weak noise
- 5x3 unimodal functions severe noise
- 3x3 multimodal functions severe noise

# Experimental Setup

→ For each function and each dimension  $d(=2;3;5;10;20;40)$ , 15 trials are carried out on 15 different function instances

Input to the algorithms:

→ search space dimension  $d$

→ search domain  $[-5, 5]^d$

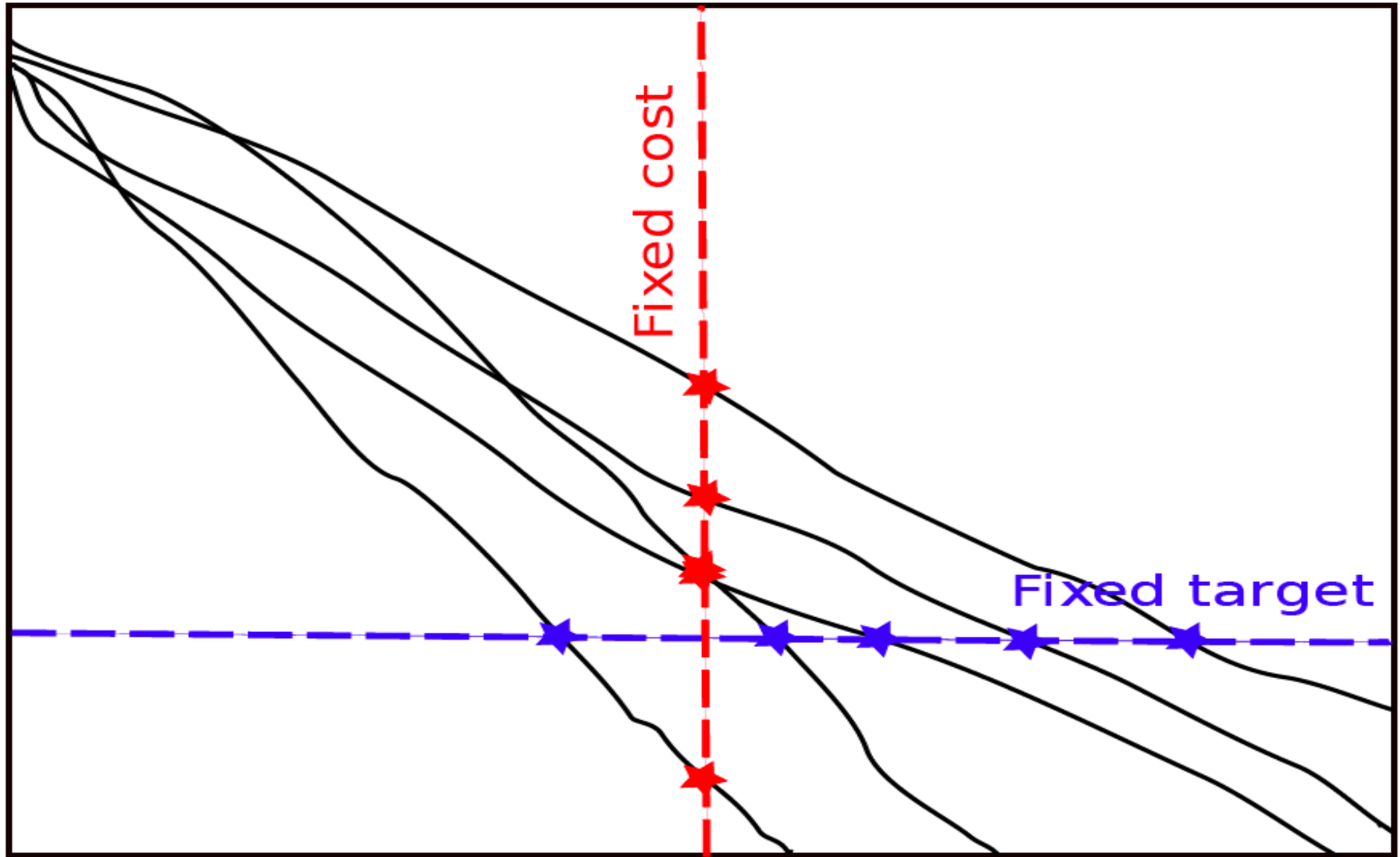
→ testbed under consideration (noise-free / noisy)

[→ target function value, only for termination criteria]

# How to measure performance?

**fixed-cost**

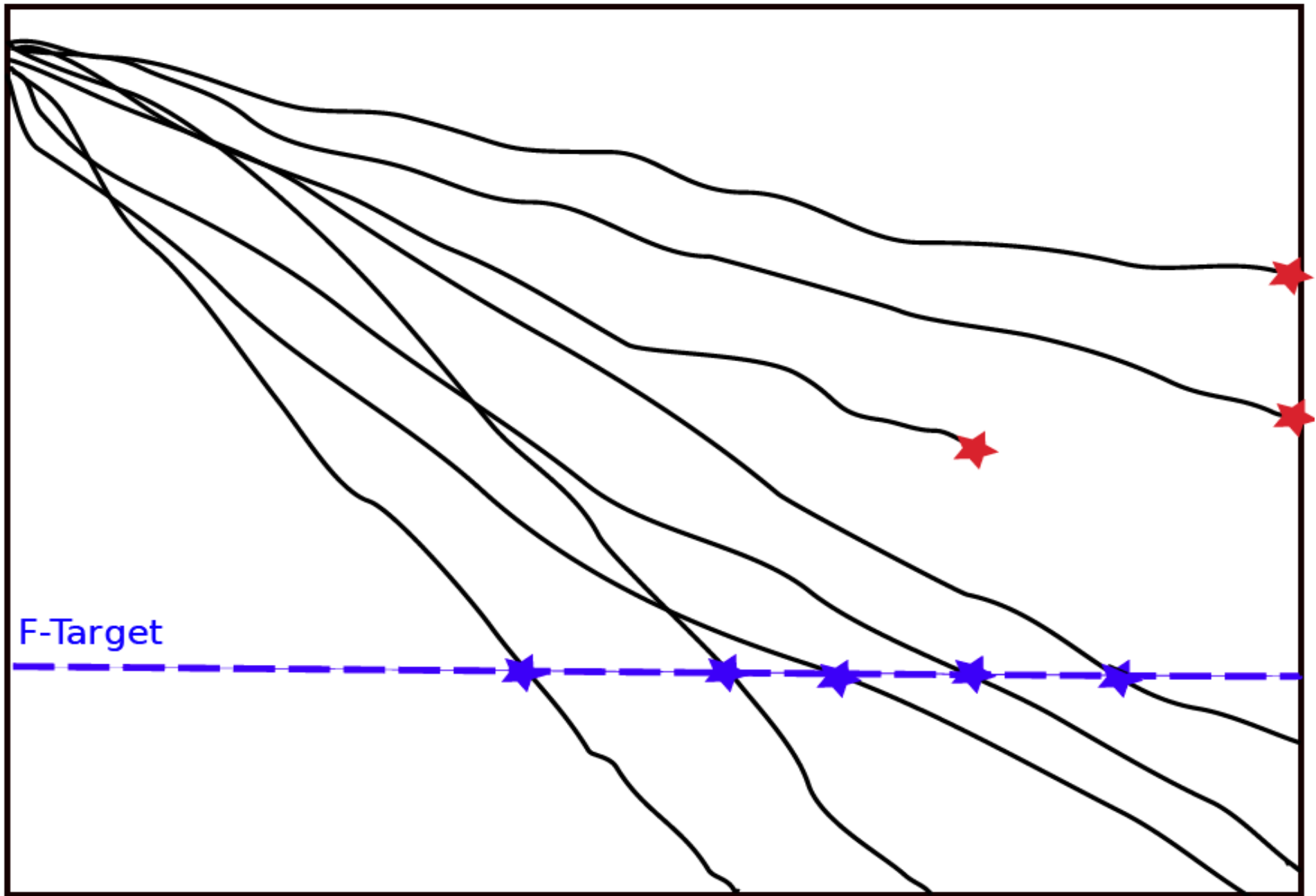
**fixed-target**



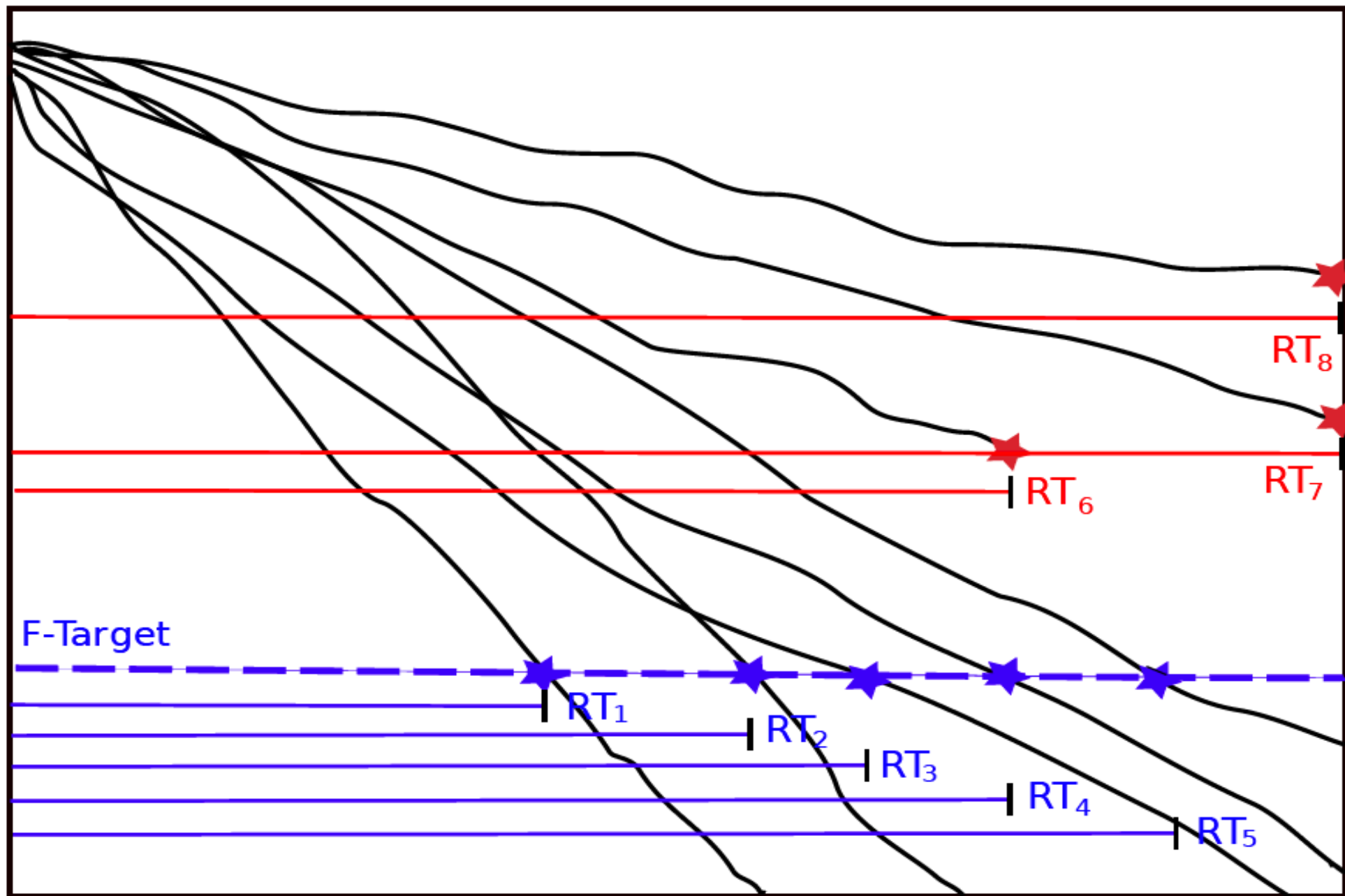
Black curves: best achieved function value versus number of function evaluations (time)



# Collect Running Time (RT) to reach F-target



# Collect Running Time (RT) to reach F-Target

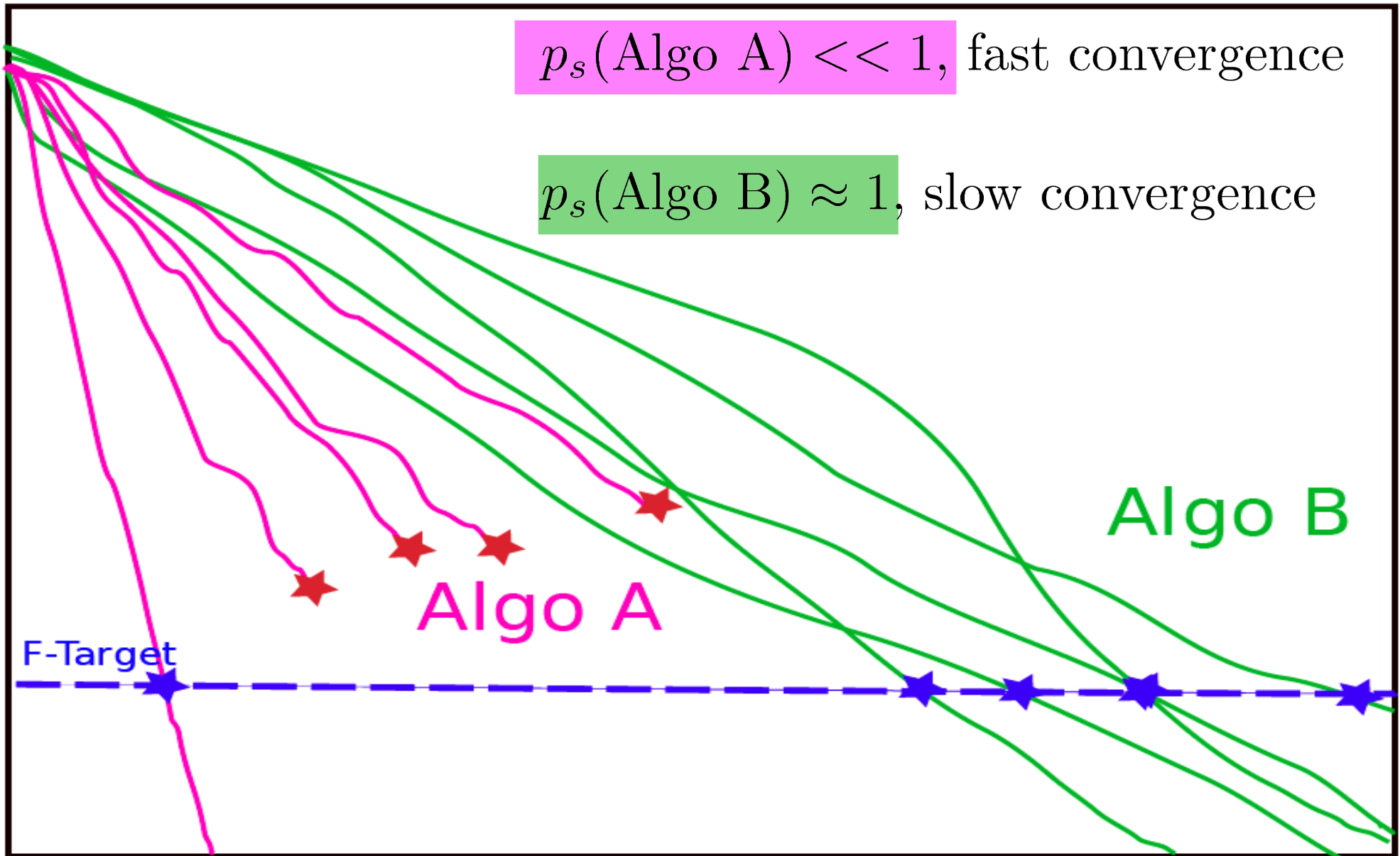


# Which performance measure?

to compare the two following scenario?

$p_s(\text{Algo A}) \ll 1$ , fast convergence

$p_s(\text{Algo B}) \approx 1$ , slow convergence



Compare Running Time of algorithms restarted  
independently till success:

Algo Restart A:



$$p_s(\text{Algo Restart A}) = 1$$

Algo Restart B:



$$p_s(\text{Algo Restart B}) = 1$$

Running Time of Restarted Algorithm:

$$RT^r = \sum_{i=1}^{N-1} RT_{\text{unsuccessful}}^i + RT_{\text{successful}}$$

$N$ =Geometric RV with parameter  $p_s$  [ $E(N) = \frac{1}{p_s}$ ]

Expected Running Time (ERT) of Restarted Algo:

$$E[RT^r] = \frac{1 - p_s}{p_s} E[RT_{\text{unsuccessful}}] + E[RT_{\text{successful}}]$$

# Estimator for ERT

$$\text{ERT} = E[RT^r] = \frac{1-p_s}{p_s} E[RT_{\text{unsuccessful}}] + E[RT_{\text{successful}}]$$

Estimator for ERT:

$$\hat{p}_s = \frac{\# \text{ succ}}{\# \text{ Runs}}$$

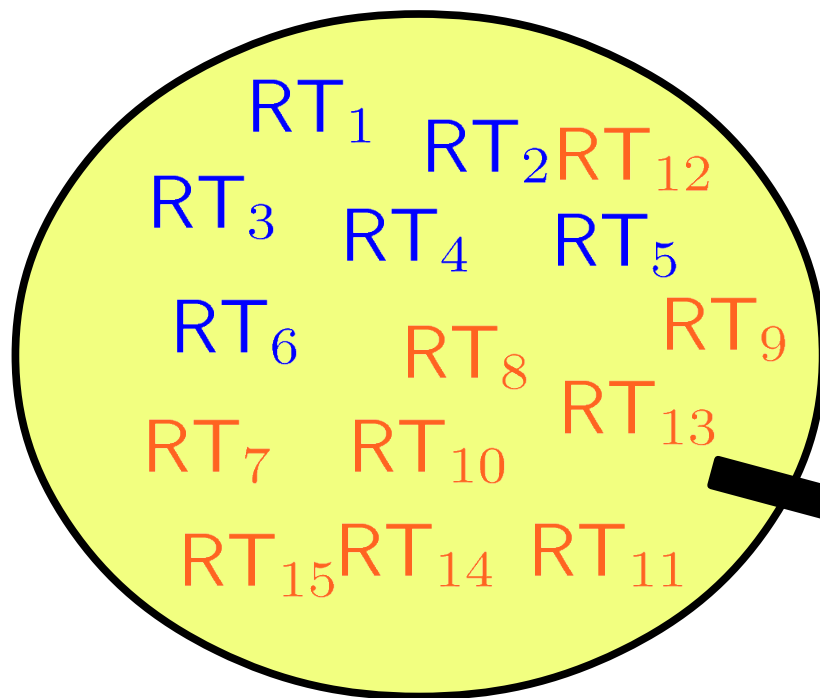
$\widehat{RT}_{\text{unsucc}}$  = Average Evals of unsuccessful runs

$\widehat{RT}_{\text{succ}}$  = Average Evals of successful runs

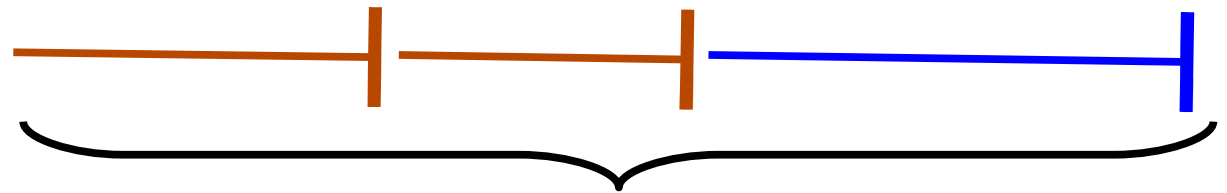
$$\widehat{\text{ERT}} = \frac{\# \text{ Evals}}{\# \text{ success}}$$

# Obtaining single instances of $RT^r$

Generate a distribution of  $RT^r$  from collected data:



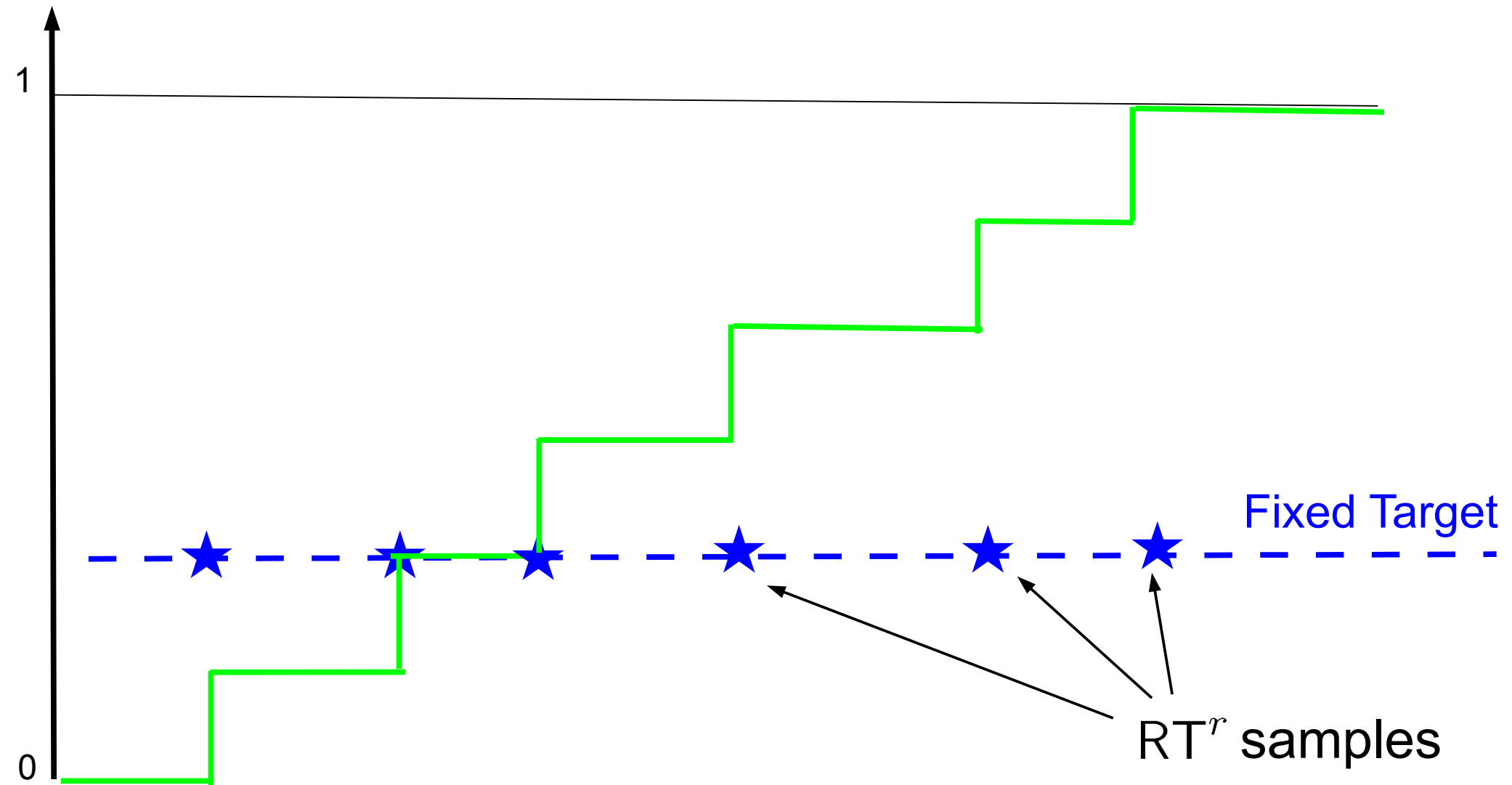
Sample with replacement till obtaining a successful run



one instance of  $RT^r$

REPEAT 100 times

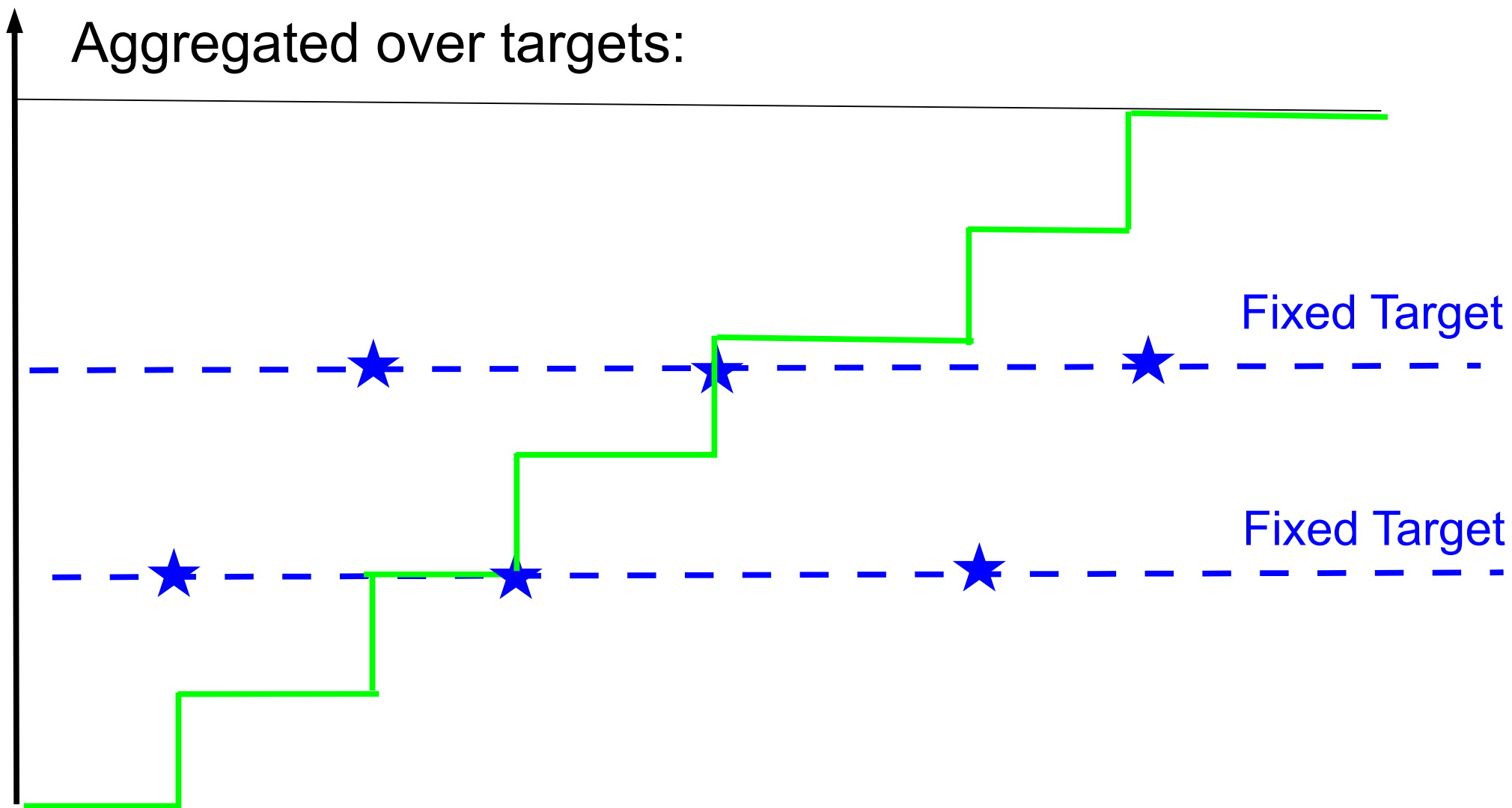
# Empirical Cumulative distribution of $RT^r$



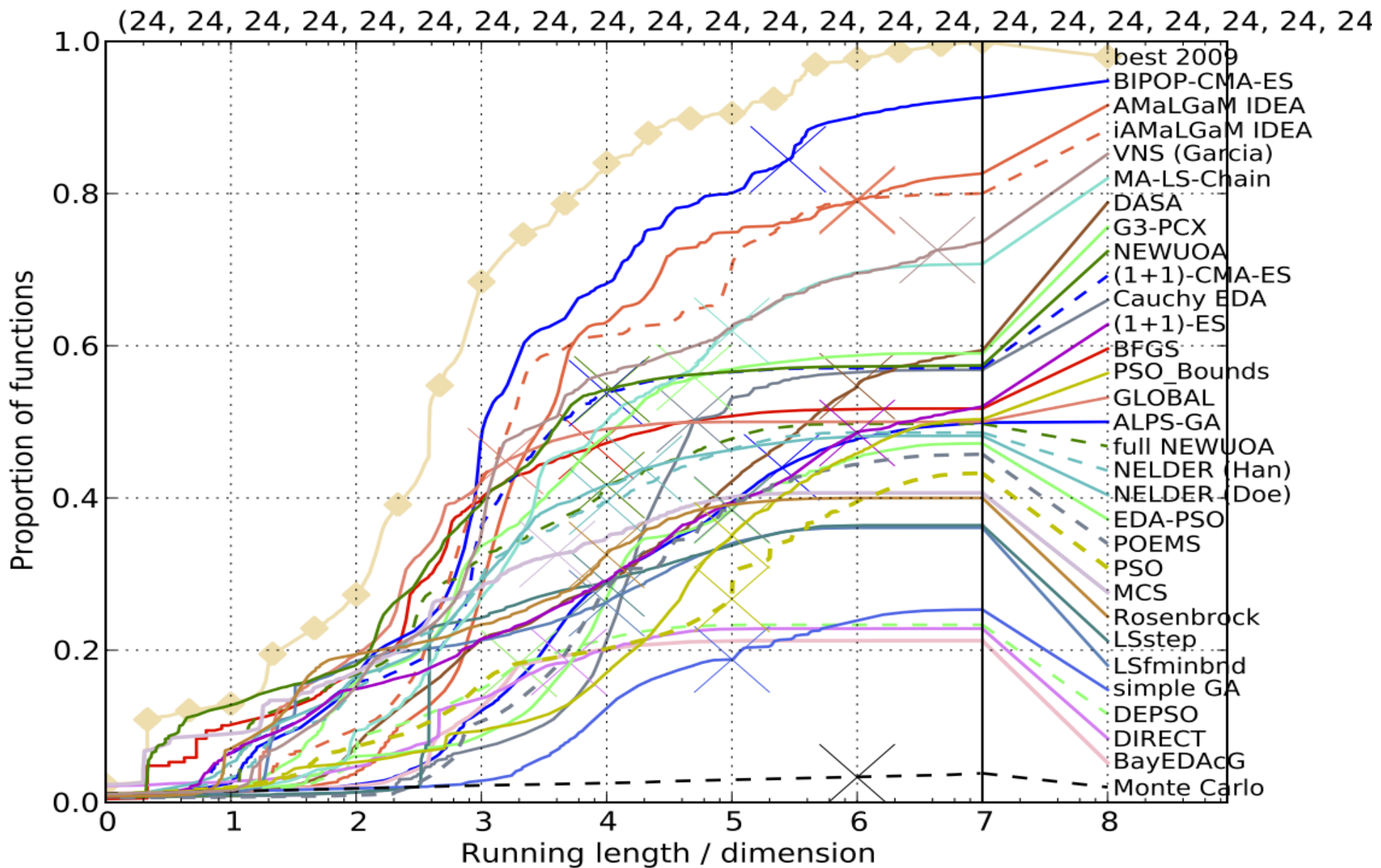


# Empirical Cumulative distribution of $RT^r$

Aggregated over targets:



# Empirical cumulative distributions of $RT^r$



## % SEPARABLE

- 1 Sphere
- 2 Ellipsoid separable with monotone x-transformation, condition 1e6
- 3 Rastrigin separable with both x-transformations "condition" 10
- 4 Skew Rastrigin-Bueche separable, "condition" 10, skew-"condition" 100
- 5 Linear slope, neutral extension outside the domain (not flat)

## % LOW OR MODERATE CONDITION

- 6 Attractive sector function
- 7 Step-ellipsoid, condition 100
- 8 Rosenbrock, original
- 9 Rosenbrock, rotated

## % HIGH CONDITION

- 10 Ellipsoid with monotone x-transformation, condition 1e6
- 11 Discus with monotone x-transformation, condition 1e6
- 12 Bent cigar with asymmetric x-transformation, condition 1e6
- 13 Sharp ridge, slope 1:100, condition 10
- 14 Sum of different powers

## % MULTI-MODAL

- 15 Rastrigin with both x-transformations, condition 10
- 16 Weierstrass with monotone x-transformation, condition 100
- 17 Schaffer F7 with asymmetric x-transformation, condition 10
- 18 Schaffer F7 with asymmetric x-transformation, condition 1000
- 19 F8F2 composition of 2-D Griewank-Rosenbrock

## % MULTI-MODAL WITH WEAK GLOBAL STRUCTURE

- 20 Schwefel  $x \cdot \sin(x)$  with tridiagonal transformation, condition 10
- 21 Gallagher 101 Gaussian peaks, condition up to 1000
- 22 Gallagher 21 Gaussian peaks, condition up to 1000, 1000 for global opt
- 23 Katsuuras repetitive rugged function
- 24 Lunacek bi-Rastrigin, condition 100